**Coventry University** 

Faculty of Engineering, Environment & Computing

**Department of Mechanical, Aerospace & Automotive Engineering** 



# 7166MAA Project Report

# FEA modelling of the aluminium alloy graphene-based composite plate for the launch vehicle external fuel tank structural application

Submitted in partial fulfilment of the requirements for the degree of Masters of Science

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Declaration: The work described in this report results from my investigations. All sections of the text and results that have been obtained from other work are fully referenced. I understand that cheating and plagiarism constitute a breach of University Regulations and will be dealt with accordingly.

Signed:

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Date: 13.08.2023

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## Abstract

The primary aim of this research is to investigate the structural uses of an aluminium alloy with a composite plate made of graphene in launch vehicle fuel tanks. To evaluate the viability and performance of the composite plate in this application, finite element analysis (FEA) modelling is used. The study aims to analyse the composite plate's mechanical behaviour, thermal characteristics, and structural integrity under various loading scenarios, such as mechanical and thermal loads, stress, and strain. The outcomes of the FEA model are compared with the materials currently used in the external fuel tanks of launch vehicles. A cost analysis of the production process is also carried out to determine whether using the graphene-based composite plate is economically feasible. The study intends to provide light on the benefits, difficulties, and constraints related to the structural components of launch vehicle fuel tanks made of graphene-based composites. The results of this study have the potential to advance the discipline of aeronautical engineering and establish the framework for upcoming advances in materials science and design optimisation for launch vehicle applications.

Nomenclature- Finite Element Analysis (FEA), Carbon Nanotubes (CNT), Liquid Oxygen (LOX), Liquid Hydrogen (LH2), External Fuel Tank (EFT).

# **1.0 Introduction**

The aerospace sector is continually looking for novel ways to improve the effectiveness and performance of launch vehicles. To retain structural integrity during launch and space missions, fuel tanks, as a crucial component of these vehicles, require materials that can withstand extreme conditions. Due to its remarkable mechanical qualities, lightweight, and thermal conductivity, graphene-based composites have recently attracted increasing interest in aircraft applications. Finite element analysis (FEA) modelling is the primary study tool to examine the viability of utilising an aluminium alloy with a graphene-based composite plate for structural applications in the fuel tanks of launch vehicles (Velram et al., 2018).

The materials currently used to build fuel tanks for launch vehicles have limitations, including weight, corrosion resistance, and mechanical qualities. To overcome these obstacles and deliver improved performance, it is necessary to investigate new materials and technologies. It offers enormous promise to improve structural grades to incorporate graphene, a two-dimensional carbon material, into an aluminium alloy matrix. Graphene has remarkable mechanical, thermal, and electrical properties. This study's primary objective is to evaluate the viability of using a composite plate made of graphene and aluminium for the structural use of fuel tanks in launch vehicles. This study uses FEA modelling to assess the suggested composite material's mechanical behaviour, performance, and durability under various situations, such as heat loads, mechanical stresses, and strain (Jayaseelan et al., 2022).

This research involves a comprehensive literature review on the FEA modelling of aluminium alloys with graphene-based composites for aerospace structural applications. The study consists in developing a model utilising the FEA technique and validating it against experimental data to ensure accuracy and dependability. Numerous analyses will evaluate the composite material's performance under various loading conditions, including thermal, stress, and strain studies.

#### Figure 1:



External Fuel Tank of Launch Vehicle

*Note*. From *External Fuel Tank of Launch Vehicle*, by Pinterest, n.d., (https://www.pinterest.com/pin/439663982371779097/)

The novel concept of this research is the incorporation of graphene-based composites into the structural design of launch vehicle fuel containers. This novel approach can significantly enhance strength, weight reduction, and corrosion resistance compared to conventional materials. In addition, FEA modelling provides a cost-effective and efficient method for evaluating the feasibility and performance of the proposed composite material before conducting physical tests.

Based on the preliminary investigation and previous research in the field, integrating an aluminium alloy with a graphene-based composite plate can improve the structural integrity and performance of launch vehicle fuel containers. The graphene reinforcement is anticipated to enhance the composite material's mechanical properties, such as tensile strength and hardness. In contrast, the aluminium alloy matrix provides corrosion resistance and structural stability. FEA modelling shows that the proposed composite material will exhibit superior performance under various loading conditions compared to the current materials used in fuel tank construction.

#### **1.1 Problem Description**

Launch vehicles are crucial to space exploration, requiring high-performance materials that withstand extreme conditions. Their materials limit the launch vehicle fuel tank's weight, strength, and thermal stability. The above considerations have prompted the study of alternate materials that might increase launch vehicle efficiency and safety.

Due to its strength-to-weight ratio, aeroplanes use aluminium alloys extensively. However, modern space travel requires materials with remarkable properties beyond ordinary alloys. Graphene-based composites' mechanical, thermal, and electrical characteristics make them intriguing materials. Graphene in aluminium alloys may improve launch vehicle fuel tanks. However, this idea raises essential questions. The structural usage of an aluminium alloy and a graphene-based composite plate in launch vehicle fuel tanks is complex and requires a detailed investigation. The modelling and assessment of composite materials under various conditions might benefit from Finite Element Analysis (FEA) models. However, several criteria must be considered to implement this revolutionary material notion successfully. In space exploration, launch vehicles need innovative materials that can survive harsh temperatures and operate well. Current launch vehicle exterior fuel tank materials are limited in weight, strength, and thermal stability. This has led to the research of alternate materials that may improve launch vehicle efficiency and safety.

The strength-to-weight ratio of aluminium alloys makes them popular in aircraft. However, contemporary space exploration requires materials with superior qualities to previous alloys. Due to their mechanical, thermal, and electrical properties, graphene-based composites seem promising. The incorporation of graphene into aluminium alloys might improve launch vehicle fuel tanks, but it poses numerous essential problems.

The viability of using an aluminium alloy and a graphene-based composite plate for launch vehicle fuel tank structural purposes is complex and requires more research. To simulate and evaluate these composite materials under different situations, Finite Element Analysis (FEA) modelling is helpful. To apply this innovative material idea successfully, many factors must be addressed.

# 1.2 Project Aim

Investigation of the feasibility of using aluminium alloy with a graphene-based composite plate for structural application in the fuel tanks of launch vehicles through FEA modelling.

# **1.3 Project Objectives**

- Literature review of FEA modelling of the aluminium alloy with a graphene-based composite plate for the launch vehicle external fuel tank structural application.
- Developing a model and validating it against experimental data.
- Analysing composite plates under various conditions such as thermal, mechanical loads, stress and strain, etc.
- Analysing the external fuel tank of the launch vehicle under various conditions.
- Comparing results with the current material used for the external tank of the launch vehicle.
- Identifying any challenges or limitations.

# 2.0 Literature Review

## 2.1 Material

- Aluminium metal matrix composites (MMCs) have been thoroughly researched for wear across several operating settings. The authors examined how average load, sliding velocity, sliding distance, and reinforcements impact the composite's wear rate and coefficient of friction (COF). Delamination, adhesive wear, abrasive wear, and fretting are well-studied. Stir casting, powder metallurgy, and friction stir processing have produced aluminium MMCs. Production methods depend on composite material qualities. Stir casting is inexpensive, but friction stir processing increases microstructural and mechanical characteristics. Pin-on-disc wear experiments measured aluminium MMCs' wear rate and COF. SEM examined the worn surface's shape and causes (Samal et al., 2020).
- Powder metallurgy, stir casting, and squeeze casting have been studied to uniformly distribute 2D graphene nanoplatelets into the matrix. The hardness, tensile strength, and ductility of Metal Matrix Composites (MMCs) are significantly affected by 2D–graphene nanoplatelets dispersion. The proper distribution of 2D–graphene nanoplatelets can increase the grain refinement and stable intermetallic phases, improving metal matrix composite's (MMCs) mechanical properties (Pazhani et al., 2023).
- Multiple investigations have investigated the effects of graphene incorporation into an aluminium matrix. It has been observed that incorporating graphene improves the composite's mechanical properties up to a certain point. Among the reinforcement mechanisms are effective load transfer via Orowan looping of nanoparticles, load transfer from the aluminium matrix to graphene, dislocation strengthening due to coefficient mismatch, and grain refinement. Several fabrication techniques have been investigated, with powder metallurgy being the most common technique for obtaining a decent graphene dispersion within the matrix (Md Ali et al., 2021).
- Rajak et al. (2019) provided a comprehensive critical overview of composite materials and manufacturing studies. The study compared research methods, identified gaps in the present corpus of research and stress the importance of these results to future growth in the field. This study also examines the idea that combining naturally biodegradable chemicals with synthetic components might produce eco-friendly composites with increased mechanical properties. Composite material's characteristics and manufacture have been studied using numerous ways. The authors have optimised processes, improved fibre arrangement and structure, and examined how matrix components affect composite performance. Nanomaterials may improve composites, according to a nanotechnology study. Automation of industrial processes to improve efficiency has been a significant research focus. 3D printing composites may create complicated and customised structures while avoiding material waste (Rajak et al., 2019).
- Despite the extensive research on graphene nanocomposites, several knowledge deficits must be addressed. First, most analyses of these nanocomposites have focused on their elastic behaviour, limiting our comprehension of their inelastic deformation. To advance this discipline, future research should investigate the inelastic behaviour of graphene nanocomposites, particularly in terms of crack initiation, fracture, and structural injury. In addition, there is a dearth of research on specific fracture defects, such as internal cracks and inclines, which are essential for comprehending the failure mechanisms of graphene

nanocomposites. Moreover, the vibration analysis of graphene nanocomposites has primarily focused on free and forced vibrations, whereas the study of damped oscillations remains relatively unexplored. By addressing these voids, the hope is to understand better the mechanical behaviour and failure mechanisms of graphene nanocomposites. This knowledge will contribute to developing more accurate and trustworthy models for predicting the performance and durability of nanocomposites based on graphene (Dahiya & Bansal, 2022).

- Despite using mechanical exfoliation, and chemical reduction, graphene with outstanding properties is still challenging to produce. Authors found that nanocomposites using graphene fillers have higher modulus and tensile strength. Graphene fillers' distribution inside the polymer matrix has also been an issue, driving research to optimise interfacial interactions and achieve homogenous dispersion to reduce agglomeration. To make graphene nanocomposites, researchers have used several methods. To improve graphene compatibility with the polymer matrix, functionalisation is often used. Hybrid fillers, which combine graphene with other nanomaterials like carbon nanotubes or metal oxides, have also been studied to solve graphene's specific restrictions and achieve customisable characteristics. Solution blending, melt mixing, and electrophoretic deposition are also used to incorporate graphene into the polymer matrix (Iqbal et al., 2020).
- Direct Digital Manufacturing (DDM) is one novel process for creating GNP-reinforced aluminium matrix composites that is both unique and efficient. DDM uses considerable plastic strain and frictional and deformation methods to generate heat. This synergistic impact promotes dynamic recovery and recrystallisation, uniformly dispersing Graphene Nanoplatelets (GNPs) and forming ultra-fine microstructures. The technology reduces processing time and improves microstructural manipulation. DDM works in many metal matrix composites, demonstrating its versatility and potential. Despite the favourable results of DDM on other metal matrix composites, GNP-reinforced aluminium matrix composite investigations are expected. Direct Digital Manufacturing (DDM) study on the effects of processing factors on these composites' microstructure and mechanical properties must be included. Although specialised studies have explored the mechanical properties of composites, there need to be more studies on improving strength-ductility, which is critical in real-world applications. This research is relevant to the study's aims. Direct Digital Manufacturing (DDM) of aluminium matrix composites containing Graphene Nanoplatelets (GNP) may solve GNP dispersion and interfacial bonding issues. This work addresses literature gaps and analyses processing parameters to improve composite strength-ductility efficiency and mechanical performance (Xie et al., 2022).
- Hot extrusion is the primary method for compacting graphene nanosheets and aluminium particles into a billet. Hot rolling then improves the composites' microstructure and mechanical properties. Extrusion-MPHR hybrid deformation improves graphene nanoplatelet dispersion and interfacial bonding, enhancing mechanical properties. GNS content, extrusion parameters, and hot rolling circumstances have been studied in composites' microstructure and mechanical properties. Interfacial reaction products, such as Al4C3, at the interface between aluminium and graphene nanosheets and their impact on the composite material have also been studied. However, hybrid deformation's unique effect on graphene nanosheet dispersion and interface bonding must be better understood. Graphene nanoplatelets aluminium composites are progressing, although certain areas need additional research and development. First, hybrid deformation's effects on composites' grain boundary network distribution and interfacial structure should be

studied more. To optimise composites' mechanical properties, these changes must be understood. Despite GNS/Al composite strengthening studies, load transfer strengthening efficiency and interaction with the interfacial structure must be thoroughly evaluated. Interfacial transition zones might increase load transmission during hybrid deformation. A quantitative appraisal needs to be improved (Pu et al., 2021).

- A prevalent technique is mechanical stir casting, which entails mixing multi-walled carbon nanotubes and Mg (wettability agent) with molten A356 alloy and solidifying. Wu, Chang, Gurkan, and Cebeci utilised the Taguchi method, a robust experimental design, to optimise composite development parameters. They discovered that the quantity of multi-walled carbon nanotubes, magnesium, and duration of mechanical agitation significantly affected the composite's mechanical properties. The role of mechanical agitation in dispersing multi-walled carbon nanotubes within the matrix has been extensively investigated. Wang et al. and Alhawari et al. discovered that mechanical agitation enhanced the homogenous distribution of reinforcement materials within an aluminium matrix. In addition, Mg is frequently used as a wettability agent to improve the hydration and interfacial bonding between multi-walled carbon nanotubes and the aluminium matrix. Bakr et al. reported that adding 0.75 % Mg to the liquid enhanced its wettability. Although significant progress has been made in fabricating and characterising multi-walled carbon nanotubes -A356 composites, certain limitations persist. Determining multi-walled carbon nanotubes and Mg content within the matrix continues to be complicated. Moreover, although several studies have investigated the effects of multiwalled carbon nanotube content, mechanical agitation, and Mg on mechanical properties, a comprehensive optimisation strategy is still required to achieve an optimal combination of these parameters (Hanizam et al., 2019).
- The distinctive qualities of graphene, such as its two-dimensional flaky structure and substantial surface area, have been highlighted. These qualities make graphene an appealing reinforcing material for aluminium matrices. Graphene reinforcement particles are distributed uniformly, despite some investigations reporting grain boundary aggregation at more significant graphene weight percentages. The composites were successfully constructed using hot extrusion and microwave processing processes, which allowed them to satisfy the requirements for structural usage in the super lightweight external fuel tank. This study's specific objectives are to examine the process by which graphene adheres to the aluminium matrix and to assess the impact of various graphene weight percentages on the microstructure and mechanical characteristics of the composites (Jayaseelan et al., 2022).
- Many authors have focused on developing corrosion-resistant coatings for aluminium alloys. Polymer electrolyte oxide (PEO) coatings have gained popularity because of their hardness, thickness, and corrosion resistance. Graphene nanomaterials in coatings have been widely studied for corrosion protection. Graphene's electron-rich structure and colossal surface area make it a promising corrosion inhibitor for metal substrates. Plasma electrolytic oxidation (PEO) coatings have been tested for corrosion resistance utilising graphene. Electrochemical impedance spectroscopy (EIS) and potentiodynamic polarisation curve measurements are routinely used to assess coating corrosion behaviour. The scanning Kelvin probe (SKP) has also been used to compare the Volta potential of coated and uncoated materials, providing microelectrochemical insights into corrosion. Graphene-incorporated PEO coatings' corrosion resistance has been studied. The study has several undiscovered regions. First, no literature compares graphene concentrations

and their effects on PEO coating corrosion resistance. Graphene's processes for improving PEO coatings' corrosion resistance still need clarification. Scalability and industrial viability must also be investigated (Liu et al., 2019).

- Ball milling is one of the methods which disperses graphene nanoplatelets (GNPs) in aluminium (Al) powders, enhancing nano-scale reinforcement distribution. Process control agents (PCA) such as polydimethylsiloxane (PDMS) and milling time and speed have been studied. Interfacial bonding in graphene nanoplatelets (GNPs) and aluminium (Al) composites has been assessed using various methods. SEM and Raman's spectroscopy have been used to study graphene shapes and defects. XPS and electron diffraction studies identified interfacial products Al<sub>4</sub>C<sub>3</sub>, Al<sub>2</sub>OC, and Al<sub>2</sub>O<sub>3</sub>. DFT has also been used to calculate interfacial shear strength. GNP-Al composites have been studied for their mechanical properties. Interfacial bonding and load transfer efficiency have received little attention. To maximise composite mechanical properties, one must understand interfacial bonding processes. Polydimethylsiloxane (PDMS) as a process control agent (PCA) has prevented the formation of unwanted aluminium carbide (Al<sub>4</sub>C<sub>3</sub>) and aluminium oxide (Al<sub>2</sub>OC). More research is needed to understand the processes and improve interface bonding (Ju et al., 2020).
- The authors have applied FSAM to aluminium-lithium alloys, specifically 2060 Al-Li, the third-generation alloy. FSAM, a solid-state additive manufacturing method, avoids meltbased AM difficulties. The authors used laser-assisted powder bed fusion (L-PBF) to build Al-14Li alloy blocks with fissures and inclusions. They used wire arc additive manufacturing (WAAM) to deposit AA2050 Al-Li alloy with microstructural variations. They examined the laser melting dimension (LMD) of 2A97 Al-Li alloy and found non-uniform microstructures and poor mechanical characteristics. FSAM can produce structurally efficient magnesium alloy components and 7N01-T4 Al alloy with finer and more uniform microstructures and moderately enhanced automatic features. Traditional melt-based AM techniques generally have coarse microstructures and internal flaws due to the melting-solidification cycle. FSAM avoids metallurgical defects during melting and solidification in solid-state additive manufacturing. Compact and fine FSAM granules improve mechanical characteristics. FSAM also causes dynamic recrystallisation during intense plastic deformation and heat input, producing fine equiaxed granules between 2 and 5 m in the nugget zone (Jiang et al., 2023).
- However, despite these advancements, several voids in the existing literature must be addressed. First, more research should be conducted on the combined influence of copper, alumina, and graphene on the properties of aluminium composites. Although individual studies have examined the effects of these components, a comprehensive comprehension of their synergistic interactions still needs to be improved. Fixing this gap is essential for optimising aluminium composites that use multiple reinforcements. More research needs to be conducted on the effects of secondary processes, specifically hot rolling, on the microstructure and properties of aluminium composites. Much research has concentrated solely on the powder metallurgy technique, ignoring the potential improvements that can be attained through subsequent processing stages. It is essential to investigate the effects of hot rolling as a secondary procedure to optimise the properties of aluminium composites and reveal the mechanisms underlying the improvements (Bitar et al., 2022).
- While individual reinforcements have been exhaustively examined, research on hybrid composites that combine multiple mounts is limited. Sometimes, the optimal combination of reinforcement particles and their respective volume fractions for attaining the most

significant wear performance is not well-defined. Wear behaviour under varied loads and sliding conditions: The wear behaviour of Al-Si composites under varying loads and sliding velocities requires additional research. Inadequate study of wear mechanisms: It is essential to identify the factors contributing to wear resistance and degradation by thoroughly investigating wear mechanisms in various composites (Nithesh et al., 2021).

- Most synthesis methods use dangerous substances or excessive energy, harming the environment. Assessing and managing these impacts is essential for using graphene-based devices. Industrial graphene production is challenging. Scalable, cost-effective technologies like FJH need optimisation and validation to satisfy commercial expectations. Refuse materials for graphene production are untested. Research should find suitable carbonaceous sources and evaluate their environmental impact (Edward et al., 2023).
- Carbon nanotube yarns have demonstrated repeatable, stable resistance behaviour and low density, making them appropriate for real-time monitoring of composite deformation and fracture propagation. Moreover, incorporating carbon nanotube fibres into an epoxy matrix preserves their flexibility, preventing permanent fractures even after substantial deformations. Authors have also investigated multi-objective optimisation to determine the optimal graphene nanoplatelet distribution pattern and material profile for attaining desirable structural performance goals. CNT-steel composites have demonstrated potential for applications in high-pressure and high-temperature environments requiring anticorrosive and mechanically robust materials. In addition, the improvement of CNT web performance for mode I interlaminar fracture toughness has been identified as a potential area for future research, which may involve amino-functionalization. The use of carbon nanotubes in cementitious composites has the potential to overcome the functional limitations of conventional conductive additives; however, additional research is necessary to assure durability and stability. In addition to experimental characterisation, numerical analysis has been used to examine fracture behaviour, fissure initiation and propagation, and microstructural damage in CNT and graphene composites (Yadav et al., 2021).
- Nanocomposites reinforced with CNTs and graphene have been studied for their mechanical properties and fracture response. Authors have used different polymer matrices to examine many carbon nanotubes (CNT), graphene production, and nanocomposite synthesis methods. Tensile strength, Young's modulus, and fracture toughness have been studied using experimental and computational methods. Authors have studied how carbon nanotube (CNT) and graphene concentration, dispersion, and alignment affect nanocomposites' mechanical characteristics. Since the matrix-CNT-graphene interfacial bonding determines mechanical properties, considerable study has focused on it. Examining nanocomposites' fracture behaviour has included CNT defects, inclusions, and agglomeration. They have used numerical modelling methods to predict nanocomposites' mechanical properties and fracture tendencies. FEA, MD, and micromechanics models are used. Tensile testing, fracture toughness, and interlaminar fracture tests have supported computational results (Yadav et al., 2021).
- Aluminium-graphene nanoplatelet (GNP) composites have been manufactured using numerous methods. Powder metallurgy and hot extrusion evenly distribute graphene nanoplatelets (GNPs) in the aluminium matrix. Spark plasma sintering, hot accumulative roll bonding, and hot rolling have been researched for making these composites. Composites' mechanical and thermal properties have been studied using various

processing methods. The series, parallel, Maxwell, Son-Frey, and Russell models have been used to estimate thermal conductivity in these composites. These models assess composites' effective thermal conductivity by considering volume percentage, shape, matrix and reinforcing thermal conductivities. Experimental studies on aluminium composites' mechanical and thermal properties, incorporating graphene nanoplatelets (GNPs), have neglected finite element modelling of heat conductivity. There are few limited element analysis studies predicting these composites' thermal properties. Given the research gap, finite element analysis may be able to accurately estimate the thermal conductivity of aluminium composites, including distributed graphene nanoplatelets (Harichandran et al., 2022).

- Stir casting is popular because it evenly distributes reinforcements and bonds the matrix and particles. Stir casting has better reinforcement distribution than other methods, improving mechanical characteristics. Researchers altered weight percentages to determine how SiC and B4C affect aluminium composite characteristics. Studies show a trade-off between mechanical parts and ductility as the B4C level enhances hardness and tensile strength but decreases elongation % (M C et al., 2020).
- Based on a literature analysis, graphene nanoplatelets (GNPs) can improve mechanical characteristics in aluminium matrix composites. Correct GNP dispersion during mechanical alloying can improve mechanical behaviour together with sintering optimisation. Composites with extended milling periods and higher GNP concentrations should be more complex. The research also optimises processing settings, investigates graphene shapes, and creates composites for real-world applications to fill gaps in the literature (Pérez-Bustamante et al., 2014).
- Extensive research has demonstrated the potential of GNFs as reinforcing agents in various materials; the investigation of GNFs as supporting agents in metals or aluminium alloys, especially aluminium alloys, still needs to be completed (Yan et al., 2014).
- The synthesis method and reinforcement material substantially affect Al nanocomposite reinforcing mechanisms and mechanical properties. For Al<sub>2</sub>O<sub>3</sub> and Al-GNP nanocomposites, particle size is a crucial factor in determining their strength and durability. In addition, impurities and the bonding quality between the matrix and reinforcement may play a significant role in the nanocomposite's overall strength (Tabandeh-Khorshid et al., 2016).

#### 2.2 FEA on Composite Plate

- Numerous ANSYS studies have examined rectangular plate buckling analysis. Hassan and Kurgan evaluated shell and solid plate models to measure buckling prediction accuracy. They stressed the importance of lattice density and found that shell models, notably Shell281, are more realistic for thinner plates. Solid models of solid-shell components, such as Solsh190, were recommended for bigger vessels because they match 3D elasticity theory answers (HASSAN AHMED HASSAN & KURGAN, 2019).
- Authors have employed various modelling strategies and numerical tools for delamination buckling analysis. The delamination behaviour is simulated using a two-sublimate model in Ansys with eight-node composite shell elements. The two sub-laminates are coupled, and the delaminated region's nodes are left uncoupled. This method provides a practical technique for modelling delaminated composite panels and demonstrates excellent agreement with theoretical predictions and prior research. Despite significant advancements in delamination buckling analysis, certain voids remain. A significant omission is the consideration of eccentricity in loading, particularly for thin panels with

close-to-surface delamination. The study in Section 5.2 highlights the significance of this factor and demonstrates that eccentricity substantially affects the distribution of buckling load and strain energy release rate. In addition, while previous research has focused on narrow near-surface delamination, mid-plane delamination has received less attention. This investigation compares the buckling behaviour in both situations (Rajendran & Song,1998).

#### 2.3 FEA on External Fuel Tank of Launch Vehicle

- Authors have tried many methods to integrate LH2 fuel tanks. Petroleum container stress distribution and deformation under different loading circumstances have been assessed using FEA. Stress intensities and structural integrity have been examined for flat, concave, and convex-concave catwalk geometries. Thermal analysis has also been crucial to study, focusing on heat transport inside fuel tanks during flight to keep LH2 in its liquid/gas phase and prevent excessive boil-off. Studies have used advanced thermal insulation and ventilation systems to maintain vessel structural integrity under fluctuating pressure and temperature. Studies have found that scaffold configurations with compressive loads may be unstable. Understanding the collapse behaviours and strengthening the catwalk require more research. Access holes might spill petrol in deformed areas (Gomez & Smith, 2019).
- Space launch vehicle container structural analysis and design have been thoroughly researched to assure prelaunch safety and reliability. The buckling and nonlinear behaviour of thin-walled structures, especially under mechanical and thermal pressures, have been essential areas of study. The Space Shuttle Standard-Weight Tank (SWT) and Superlight Weight Tank (SLT) have been examined for structural response. Launch vehicle containers are simulated using finite-element analysis (FEA). FEA can accurately anticipate buckling modes and nonlinear reactions by representing complicated geometries, loading circumstances, and material characteristics. Limit-point and bifurcation buckling studies have also been employed to capture the containers' critical behaviour under various loading situations (Michael et al., 1996).
- The aerospace industry uses analytical and empirical data-based conceptual design methodologies. These approaches suit initial design assessments but may not capture complicated subsystem relationships. Instead, Chiesa et al.'s integrated technique considers structural and aerodynamic considerations early in the design process. Finite element analysis improves vehicle performance under diverse loading circumstances, improving take-off mass predictions and design precision. Reusable space rockets require extensive structural analysis despite conceptual design advances. Many studies need to pay more attention to the complex interdependencies between subsystems, resulting in erroneous mass estimations and design inefficiencies. Chiesa et al.'s integrated technique addresses this by using structural analysis early in conceptual design. Their approach focuses on a class of launch vehicles like Venture Star, which might be applied to various configurations and mission parameters (Chiesa et al., 1999).
- Vacuum-jacketed plans with aluminium tanks give better thermal insulation and structural strength. Sandwiched structures using aerogel insulation take use of aerogels' low heat conductivity. Despite their low thermal conductivity, studies show that aerogels are too weak to store cryogenic propellant. Finite element analysis has examined cryogenic vessels' structural behaviour. Researchers have learned about insulation systems and tank designs thermal performance using MATLAB and Abacus. Research gaps still need to be addressed despite cryogenic tank design breakthroughs. Insulation with low thermal

conductivity and high mechanical strength is lacking. Structural integrity and thermal efficiency are still issues. Cryogenic propellant storage heat transfer optimisation is another need. Prolonged flights require avoiding propellant boil-off, although liquid cryogenics are small (Jaya Kumar, 2015).

#### 2.4 Reflection

The present chapter centres on a literature study examining using aluminium metal matrix composites (MMCs) reinforced with graphene nanoplatelets. The current research comprehensively evaluates several studies investigating the impact of distinct manufacturing methodologies on composite materials' wear rate and coefficient of friction. The discussion included three primary manufacturing processes: stir casting, powder metallurgy, and friction stir processing. The stir casting technique is widely used to fabricate metal matrix composites. The process involves introducing reinforcing particles into a molten metal matrix using agitation. The present study examines the effects of several factors, including stirring duration and speed, on the composites' wear rate and coefficient of friction, as reported in the reviewed literature. The experimental findings demonstrated that the incorporation of graphene nanoplatelets decreased the rate of wear and coefficient of friction, hence showing enhanced tribological characteristics of the composite materials. The assessed research also investigated powder metallurgy as an alternative manufacturing technique. The procedure entails the amalgamation of metal powders with reinforcing particles, after which compaction and sintering are performed. The research findings indicated that the effective dispersion of graphene nanoplatelets inside the metal matrix was pivotal in attaining improved mechanical characteristics. The homogeneous distribution of graphene enhanced the composites' tensile strength, hardness, and wear resistance characteristics. Friction stir processing is an emerging manufacturing technique that uses a spinning tool to agitate and blend the metal matrix and reinforcing particles. The present research examines a collection of studies that have explored the impact of various process factors, such as tool rotation speed and traverse speed, on the mechanical characteristics of composites. The findings demonstrated that graphene nanoplatelets as a reinforcing agent enhanced the composite materials' tensile strength and hardness characteristics. The literature study examined the mechanical behaviour and failure processes of graphene nanocomposites in conjunction with the exploration of fabrication techniques. The research analysed in this study investigated the deformation and fracture propagation of the composites under various loading situations. The findings demonstrated that incorporating graphene nanoplatelets significantly enhanced the composites' fracture toughness and fatigue resistance characteristics. The analysis further highlighted the techniques for integrating graphene inside the polymer matrix. The research conducted in this study examined several methodologies, including solution mixing, melt blending, and in-situ polymerisation, to disperse graphene inside the polymer matrix. The findings indicated that the dispersion of graphene had a pivotal role in enhancing the mechanical characteristics of the composites. In addition, the literature study examined the corrosion resistance properties of coatings based on graphene. The papers analysed in this research study investigated the impacts of graphene.

# 3.0 Methodology



The flowchart above illustrates the procedural steps undertaken to obtain a solution. Gaining an understanding of the sequential progression of the process would be beneficial. The initial step is doing research on the external fuel tank of the launch vehicle. The dimensional data will be inputted throughout the modelling of the external fuel tank. The subsequent step involves modelling three components: the LOX tank, Intertank, and LH2 tank. The method of assembling all parts occurs next to the design phase. The model that has been constructed is subjected to a validation process to ascertain the level of perfection in its design. The subsequent procedure is conducted via Ansys software. The input of the material characteristics will be shown. The next step entails the importation of geometric data. Subsequently, the mesh will be generated. The next step involves the application of boundary conditions, including fixed support, the influence of earth gravity (weight), wind/fuel force, and air temperature/fuel temperature. The answer will be expressed in terms of total deformation, equivalent stress, and equivalent elastic strain. The above diagram illustrates the fundamental sequence of steps in the procedure. The prescribed flowchart conducts the analysis.

#### **3.2 Model Development**

#### 3.2.1 External Fuel Tank of Launch Vehicle

The process of launching the space shuttle into orbit necessitates a substantial quantity of fuel, exceeding 2 million litres, which is consumed during each individual launch. Additionally, a pretty voluminous tank is required to contain this fuel. The most significant and most massive component of a fully fuelled space shuttle is the externally mounted fuel tank, commonly referred to as an ET by the National Aeronautics and Space Administration. This tank has a rust-coloured appearance and possesses a bullet-like form.

The external tank, with dimensions of 46.9 metres in length and 8.4 metres in diameter, serves as the primary support structure for the shuttle during its launch phase. It is crucial in absorbing the substantial thrust of around 2.7 million kilogrammes created during the blast-off process. The primary function of the external tank, however, is to supply pressurised fuel to the three hydrogen-burning main engines of the shuttle during the eight-and-a-half-minute journey into space. The engines have a propellant consumption rate of 242,000 litres per minute.

#### Figure 2:

Model of External Fuel Tank of Launch Vehicle



Transporting such a substantial amount of fuel into outer space presents considerable challenges. Specifically, almost one-quarter of the total launch weight of the shuttle, which amounts to 2 million kilogrammes (or 4.4 million pounds), is solely attributed to the importance of the fuel. However, contributing to the intricacy is the atypical composition of the power, which has only a distant resemblance to the petrochemicals commonly employed in the majority of motor vehicles.

The exterior tank is comprised of liquid hydrogen and liquid oxygen, which are extremely cold liquids that must be maintained at temperatures much below freezing, even in the typically warm climate prevalent in the Florida launch location of the shuttle. The external tank is equipped with many layers of specialised foam insulation to prevent ice formation on its outside surface in the hours leading up to the launch. During the launch, ice present on the shuttle can detach and potentially cause harm to the spacecraft (ENCYCLOPEDIA.COM, 2023).

Figure 3: Sectional Diagram of External Fuel Tank of Launch Vehicle



There are three main parts of the external fuel tank of the launch vehicle:

3.2.1.1 Liquid Oxygen Tank (LOX Tank)

The LOX tank is situated atop the External Tank (ET) and possesses an elliptical configuration, mitigating aerodynamic resistance and aerothermodynamic heating. The ogive nose portion is encompassed by a flat detachable cover plate and nosecone. The nosecone comprises a detachable conical structure that is an aerodynamic fairing for the propulsion and electrical system components. The first component of the nosecone serves as a lightning rod made of cast aluminium.

**Technical Specifications:** 

- Length = 16.6 m (16,600 mm)
- Diameter = 8.4 m (8,400 mm)
- Operation pressure: 34.7–36.7 psi (239–253 kPa) (absolute)
- Thickness = 25 mm (Lockheed Martin Space Systems Company, 2008)

#### **Figure 4:** *Liquid Oxygen Tank*



A liquid oxygen tank comprises three parts, i.e., the outer body of the tank, vortex baffles and anti-slosh baffles. The use of a vortex baffle plate within the tank serves to mitigate the occurrence of fuel surges resulting from vehicular inclines or sudden turns. In this context, a consistent fuel supply may be ensured to a fuel pump, therefore mitigating the noise resulting from fuel surges.

#### Figure 5:

Sectional Diagram of Liquid Oxygen Tank



## 3.2.1.2 Intertank

The intertank is a crucial component of a launch vehicle's external fuel tank. The portion of a vehicle separates the liquid oxygen (LOX) tank from the liquid hydrogen (LH2) tank in cryogenic propellant vehicles. The intertank contains the feedlines that transport LOX and LH2 from their respective containers to the rocket engines. These feedlines are responsible for precisely controlling and delivering propellants to the turbines. Intertank consists of pillars that support the structure to withstand all loads.

**Technical Specifications:** 

- Length: 22.6 ft (6,900 mm)
- Diameter: 27.6 ft (8,400 mm)
- Thickness: 25 mm

(Lockheed Martin Space Systems Company, 2008)

#### Figure 6:

Intertank



**Figure 7:** Sectional Diagram of Intertank



#### 3.2.1.3 Liquid Hydrogen Tank (LH2 Tank)

The liquid hydrogen (LH2) tank is a crucial component of the external fuel reservoir on cryogenic-propellant-using launch vehicles. It is designed to store liquid hydrogen and provide it to the rocket engines during launch. It comprises several beams and rods designed to endure the loads acting on the liquid hydrogen vessel. Liquid hydrogen is stored at

temperatures of -253 degrees Celsius. Using insulation systems, the LH2 tank is designed to maintain the propellant in its cryogenic state.

Technical Specifications:

- Length: 97.0 ft (29,600 mm)
- Diameter: 27.6 ft (8,400 mm)
- Operation pressure: 32–34 psi (220–230 kPa) (absolute)
- Operation temperature: -423 °F (-253 °C)
- Thickness: 25 mm (Lockheed Martin Space Systems Company, 2008)

(Lockheed Martin, 2008)

# Figure 8:

Liquid Hydrogen Tank



#### Figure 9:

Sectional Diagram of Liquid Hydrogen Tank



## **3.3 Material Properties**

Material - 2195 Aluminium alloy with 0.5% wt. Graphene

## Figure 10:





The composition of aluminium alloy 2195 consists of 4.2% copper (Cu), 1.1% lithium (Li), 0.35% magnesium (Mg), 0.35% silver (Ag), 0.15% zirconium (Zr), 0.15% iron (Fe), and 0.10% silicon (Si), with the rest portion being comprised of aluminium. This constitutes the majority of the alloy. The aerospace industry extensively employs this material for many

purposes, such as propellant tanks, gores sheets, propellant forgings, manhole covers, and feed line extrusions. The microstructure of alloy 2195 exhibits grains that possess an elongated morphology oriented orthogonally to the forging direction. The identification of aluminium-lithium alloys may be accomplished by observing the presence of very long grains oriented in the rolling direction. This characteristic is a distinctive attribute of the alloy (Nayan et al., 2015). The influence of the crystallographic microstructure of alloy 2195 on its formability is evident. The presence of a significant Bs 101h121i element may lead to diminished formability, as shown by previous research—the occurrence of planar slip results in the deformation of the component. Conversely, using a thermomechanical processing condition that yields a grain size characterised by greater equitability and fineness and a much weaker Bs texture can enhance formability (Dursan et al., 2014). The microstructural evolution of alloy 2195 under substantial strain deformation was investigated by researchers using a hot isothermal plane strain compression (PSC) testing method, which included a single shot. The flow curves recorded during PSC exhibited a moderate decrease in stiffness at elevated temperatures, along with a downward deviation of the flow curve at a strain rate of 1s<sup>-1</sup>. A study on optical microstructures revealed that specimens subjected to deformation at lower temperatures (300 °C and 350 °C) exhibited compressed grains. In contrast, samples deformed at higher temperatures (400 °C and 450 °C) displayed stress-free grains characterised by wavy grain borders. The use of electron backscattered diffraction in the analysis revealed the occurrence of dynamic recrystallisation in samples that underwent deformation at elevated temperatures and reduced strain rates. In a broader context, manipulating temperature and strain rate during thermo-mechanical processing offers the potential to modify the properties of aluminium alloy 2195, explicitly allowing for grain size regulation (Venkateswara Rao et al., 1989).

#### 3.4 FEA on Composite Plate

The static analysis is done on the 500x500x25 mm composite plate. There are several reasons to analyse composite plate.

- Finite Element Analysis (FEA) is a computational method that enables the prediction of the structural response of a composite plate subjected to various loading circumstances, including mechanical loads, temperature variations, and external forces. Making accurate predictions is crucial in developing and optimising structures to ensure they perform their intended tasks effectively.
- Conducting physical experiments on composite materials may be both time-consuming and costly. Finite Element Analysis (FEA) enables engineers to visually model various situations, saving time and cost by eliminating the need for repeated design iterations.
- Finite Element Analysis (FEA) allows for optimising composite plate designs by examining different materials, geometries, and configurations combinations. This process determines the efficient and effective method of meeting the specified performance objectives.
- Von Mises Stress

The von Mises stress is a metric used to quantify the magnitude of the equivalent stress experienced by a material during plastic deformation. The significance of this phenomenon is in its ability to provide criteria for accurately anticipating the beginning of yielding or failure in materials that exhibit ductility. The von Mises stress is a measure considering the combined influence of everyday and shear stresses. It is often used in engineering contexts to evaluate various components' structural soundness and safety. The von Mises stress is very

advantageous in scenarios characterised by isotropic yield behaviour of a material, whereby the material's response to stress is consistent regardless of the particular orientation of the applied pressure. In the field of plasticity theory and finite element analysis, it is customary to use a method for ascertaining the critical stress thresholds at which plastic deformation takes place (Thomas,1995).

#### Von Mises Strain

The Von Mises strain is a metric that quantifies a material's deformation or strain when subjected to external stress. The principle used is the von Mises yield criteria, which posits that a substance will undergo plastic deformation or yield whenever the von Mises stress is above a certain threshold. The von Mises strain is determined by evaluating the significant pressures, representing the highest and lowest strains encountered by the material along distinct orientations.

The von Mises strain is a scalar quantity that denotes the magnitude of pressure experienced by a material, considering the combined effect of many strain components. The measurement considers the cumulative impact of standard and shear stresses, assessing the material's total deformation. Structural analysis shows that this phenomenon proves advantageous when the material is exposed to intricate stress conditions.

It is used to evaluate the propensity for plastic deformation and failure of a material by using the von Mises strain calculation. The assessment aids in the determination of the structural integrity and dependability of construction when subjected to various loading scenarios.

#### > Mesh

The mesh generation process has significant importance in finite element analysis (FEA) since it involves the division of the study continuum into discrete pieces or finite elements. The mesh functions as a discretised portrayal of the geometry, enabling the computation of approximate solutions to the governing equations. The mesh may be produced either manually or automatically. In the process of manual meshing, the analyst generates the mesh by explicitly specifying the elements and nodes, taking into account the geometric characteristics and the desired degree of refinement. This methodology provides enhanced manipulation of the mesh quality and may be especially advantageous in accurately representing stress patterns at points of geometric discontinuity. In contrast, automated meshing entails using software tools to produce the mesh, using predetermined criteria such as element size, element type, and mesh density. This methodology exhibits enhanced speed and efficiency, mainly when dealing with intricate geometrical structures. Nevertheless, human meshing offers a higher degree of control compared to automated methods. The selection of mesh density or element size is of paramount importance due to its impact on the analysis's precision and computing efficiency. Using a finer mesh in computer simulations yields more precise outcomes but costs more processing resources and time. Hence, it is common to strike a balance between precision and efficiency In essence, mesh creation involves partitioning the analysis domain into discrete finite elements. The process may be executed either manually or automatically, and the selection of mesh density plays a crucial role in attaining precise and effective outcomes in finite element analysis (Wodo et al., 2011).

#### Applying loads and solution phase

Applying Loads: Loads are an essential step in finite element analysis (FEA). It involves defining the external forces, pressures, displacements, or constraints that act on the model. These loads represent the real-world conditions the structure or component will experience

during operation. The loads can be applied in various forms, such as point, distributed, pressure, thermal, or displacement constraints. The choice of load type depends on the specific analysis requirements and the behaviour of the structure under consideration. For example, point loads can represent concentrated forces or moments applied at particular locations in structural analysis. In contrast, distributed loads can represent uniform or varying loads applied over an area or along a line. Pressure loads can mean fluid or gas pressures acting on the surface of a structure, and thermal loads can represent temperature gradients or heat transfer effects. The loads should be applied in the same units as the specified model geometry and material properties. It is essential to accurately define the magnitude, direction, and location of the loads to obtain meaningful results from the analysis.

The solution phase in finite element analysis involves solving equations that represent the model's behaviour under the applied loads. This is typically done using numerical methods and iterative algorithms. The solver takes the input from the pre-processor, including the mesh, material properties, and applied loads, and calculates the unknowns of the problem, such as displacements, stresses, strains, temperatures, or any other desired output. The solver uses the finite element method (FEM) to discretise the model into more minor elements and then assembles the element equations into a global system. These equations are then solved to obtain the solution for the unknowns. The solution process involves iterating through the equations until convergence is achieved, ensuring that the calculated values satisfy the equilibrium and compatibility conditions of the model. The convergence criteria are typically based on the desired accuracy and the convergence behaviour of the solution. Once the key is obtained, post-processing techniques are used to analyse and interpret the results. This may involve generating contour plots, deformed shapes, stress distributions, or any other relevant visualisations to understand the model's behaviour under the applied loads.

#### Figure 11:

*500x500x25 mm Plate* 



In order to obtain the most precise results, it is essential to maintain exact mesh settings. Mesh size is kept at 5 mm.

Figure 12:

500x500x25 mm Plate Mesh Settings



• Boundary Conditions for FEA Analysis

#### Wind Force Calculation

The launch can be considerably impacted by wind. The prevailing wind conditions on that particular day may influence the rocket's trajectory. Powerful gusts of wind can alter both the course and rotation of the missile. The movement of wind exhibits variability in direction. However, in the context of the launch, it is advisable to conceptualise the wind as a horizontal vector perpendicular to the aircraft's vertical trajectory. In light of this circumstance, it is imperative to engage in calculations and implement model modifications to accommodate the disturbance (AC Supply, 2022).

For all the analysis, it is assumed that the launch will happen in Cornwall City, and wind will flow in the -Z Direction as the geometry is symmetric.

Highest Temperature in Cornwall =  $34^{\circ}$ C Wind Speed in Cornwall = 22 MPH = 9.835 m/s (BeachWeather, n.d.) Density of air at sea level =  $1.229 \text{ kg/m}^3$ Area of the plate hitting by air = Width x Thickness =  $0.5 \times 0.025 = 0.0125 \text{ m}^2$ Mass of the air = Density x Area =  $1.229 \times 0.0125$ Mass of the air = 0.0153 kg/mAcceleration = (Windspeed)<sup>2</sup> =  $(9.835)^2 = 96.727 \text{ m/s}^2$ Force = Mass x Acceleration Wind Force =  $0.0153 \times 96.727$ Wind Force = 1.4799 N Figure 13:

Wind Force on 500x500x25 mm Plate



#### Figure 14:

Earth Gravity on 500x500x25 mm Plate



#### Figure 15:

Fixed Support for 500x500x25 mm Plate



Figure 16:

Temperature taken for 500x500x25 mm Plate



#### 3.5 FEA on External Fuel Tank of Launch Vehicle

Finite Element Analysis (FEA) plays a pivotal role in evaluating intricate systems' structural integrity and safety, such as launch vehicles and their accompanying external fuel tanks. The external fuel tank of a launch vehicle is of critical importance since it supplies the necessary propellant for the rocket's engines.

- The launch vehicle's external fuel tank possesses a substantial propellant, rendering it a vital element of the launch vehicle. The structure must have the ability to endure the diverse range of loads and stresses encountered throughout different stages of the launch process, including liftoff, atmospheric pressures, and vibrations. Finite Element Analysis (FEA) is a valuable tool utilised by engineers to effectively simulate and analyse the response of tanks to various loads. This process is crucial in ensuring that the tank maintains its structural integrity and safety throughout its mission.
- To optimise their payload capacity, it is imperative for launch vehicles to possess minimal weight. Finite Element Analysis (FEA) enables engineers to comprehensively examine various material selections, designs, and combinations to identify the most favourable equilibrium between structural integrity and weight. The optimisation process has the potential to provide substantial cost savings through the reduction of material requirements while ensuring the preservation of safety margins.
- Finite Element Analysis (FEA) offers valuable insights into possible sources of failure inside the Electronic Funds Transfer (EFT) system. Engineers possess the capability to discern stress concentrations, places that are susceptible to buckling, and several other probable failure causes. This information assists in the identification of design adjustments aimed at eliminating or mitigating these flaws before the launch, hence minimising the potential for catastrophic failure.
- Before the construction of the external fuel tank, engineers can verify the soundness of their designs by employing Finite Element Analysis (FEA) simulations. The aforementioned validation method enables the evaluation of the tank's capacity to withstand the projected loads and stresses encountered during the launch. Identifying design problems early in development can prevent expensive redesigns and delays (Gomez & Smith, 2019).

# 3.5.1 Liquid Oxygen Tank Figure 17:



(BeachWeather, n.d.)

• Boundary Conditions for FEA Analysis

Wind Force Calculation

Highest Temperature in Cornwall =  $34^{\circ}C$ 

Wind Speed in Cornwall = 22 MPH = 9.835 m/s

Density of air at sea level =  $1.229 \text{ kg/m}^3$ 

Area of the plate hitting by  $air = 747.9741 \text{ m}^2$ 

Mass of the air = Density x Area =  $1.229 \times 747.9741$ 

Mass of the air = 919.26 kg/m

Acceleration =  $(Windspeed)^2 = (9.835)^2 = 96.727 \text{ m/s}^2$ 

Force = Mass x Acceleration

Wind Force = 919.26 x 96.727

Wind Force = 88916.79 N

Due to the RAM limitations and the massive size of the model, it has been scaled down by 1:10.

Wind Force = 88916.79 / 10

Wind Force = 8891.679 N

Figure 18:

Wind Force on LOX Tank

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Z Component	-8891.7 N (ramped) •		
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Fuel Weight Calculation

The External Fuel Tank of the Space Shuttle is a prominent illustration. As per NASA's findings, the extraterrestrial entity was equipped with distinct chambers designated for storing liquid hydrogen and liquid oxygen fuel. The Space Shuttle's main engines utilised these propellants to create thrust in the course of launch. The combustion of fuel resulted in a notable reduction in the tank's weight, causing a displacement in the overall centre of mass of the entire assembly, including the orbiter, solid rocket boosters, and the external tank. The management of this change was necessary in order to ensure the maintenance of steady flying. In the initial phases of ascent, the launch vehicle encounters the highest magnitudes of aerodynamic forces and is subject to the influences of thrust and gravity. The thrust-to-weight ratio of a vehicle is influenced by the reduction in mass resulting from fuel consumption. A greater thrust-to-weight ratio facilitates enhanced acceleration of the vehicle. Engineers meticulously compute and optimise the aforementioned ratio in order to guarantee a secure and effective ascension.

Moreover, the weight of the gasoline has an impact on the structural factors that need to be taken into account for the tank. The tank must possess the necessary structural integrity to endure the forces generated by the residual fuel, both in the first stage of ascent and during the acceleration period. The structural integrity of the tank is influenced by the alteration in internal pressure resulting from the use of gasoline. The management of the dynamic pressure change is crucial in order to avert tank buckling or failure (NASA, 2004).

(Liquid Oxygen, n.d.)

(NASA, 2011)

The density of Liquid Oxygen = 1.141 kg/L = 1.141 g/mLAmount of Liquid Oxygen in Tank = 145000 GallonsKilograms = Gallons x 3.7854 x Density Kilograms = 145000 x 3.7854 x 1.141Fuel Force = 626277.45 NFuel Force = 626277.45 NFuel Force = 62627.745 NFuel temperature =  $-147.222^{\circ}\text{C}$ 

# Figure 19:

Fuel Force on LOX Tank

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# Figure 20:

LOX Fuel Temperature



# Figure 21:

Earth Gravity on LOX Tank

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Figure 22:

Fixed Support for LOX Tank

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# 3.5.2 Intertank Figure 23:



• Boundary Conditions for FEA Analysis

#### Wind Force Calculation

Highest Temperature in Cornwall =  $34^{\circ}$ C

Wind Speed in Cornwall = 22 MPH = 9.835 m/s

Density of air at sea level =  $1.229 \text{ kg/m}^3$ 

Area of the plate hitting by air =  $182.087 \text{ m}^2$ 

Mass of the air = Density x Area =  $1.229 \times 182.087$ 

Mass of the air = 223.785 kg/m

Acceleration =  $(Windspeed)^2 = (9.835)^2 = 96.727 \text{ m/s}^2$ 

Force = Mass x Acceleration

Wind Force = 223.785 x 96.727

Wind Force = 21646.044 N

Due to the RAM limitations and the massive size of the model, it has been scaled down by 1:10.

(BeachWeather, n.d.)

Wind Force = 21646.044 / 10

Wind Force = 2164.6044 N

### Figure 24:

Wind Force on Intertank



#### Figure 25:

Earth Gravity on Intertank

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### Figure 26:

Fixed Support for Intertank

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- Definition	Graph 7 Tabular Data	<del>,</del>
Type Fixed Support	50	
Suppressed No	60.	

# 3.5.3 Liquid Hydrogen Tank Figure 27:

LH2 Tank Mesh Settings



(BeachWeather, n.d.)

• Boundary Conditions for FEA Analysis

Wind Force Calculation

Highest Temperature in Cornwall =  $34^{\circ}C$ 

Wind Speed in Cornwall = 22 MPH = 9.835 m/s

Density of air at sea level =  $1.229 \text{ kg/m}^3$ 

Area of the plate hitting by  $air = 1603.89 \text{ m}^2$ 

Mass of the air = Density x Area =  $1.229 \times 1603.89$ 

Mass of the air = 1971.18 kg/m

Acceleration =  $(Windspeed)^2 = (9.835)^2 = 96.727 \text{ m/s}^2$ 

Force = Mass x Acceleration

Wind Force = 1971.18 x 96.727

Wind Force = 190666.41 N

Due to the RAM limitations and the massive size of the model, it has been scaled down by 1:30.

Wind Force = 190666.41 / 30

Wind Force = 6355.547 N

Figure 28:

Wind Force on LH2 Tank

Outline		4	
Filter: Name	*	A: Static Structural	ANSYS
1 🗟 🖉 🏷 🖽	S] \$1	Time: 60. s	2019 <b>R1</b>
Image: Construction     Image: Construction       Imag		Force: 6955.5 N Component: 0,0,-6955.5 N	ACADEMIC
Details of "Force"		a 0.00 450.00 900.00 (mm) Z <sup>2</sup>	× ×
- Scope		225.00 675.00	
Scoping Method	Geometry Selection	11100 07500	
Geometry	6 Faces	Geometry / Print Preview A Report Preview /	
- Definition		Granh & Tabular Data	
Туре	Force	Orașin	
Define By	Components	60. Steps time (3) (* A(14) (* 114) (* 2(14)	
Coordinate System	m Global Coordinate System		
X Component	0. N (ramped)	-6355.5	
Y Component	0. N (ramped)	60.	
Z Component	-6355.5 N (ramped)		
Suppressed	No		

(Liquid Hydrogen, 2023)

(NASA, 2011)

Fuel Weight Calculation

The density of Liquid Oxygen = 0.07085kg/L = 0.07085 g/mL Amount of Liquid Oxygen in Tank = 390000 Gallons Kilograms = Gallons x 3.7854 x Density Kilograms = 390000 x 3.7854 x 0.07085 Fuel Force = 1042420.41 N Fuel Force = 1042420.41 / 30 Fuel Force = 34747.347 N Fuel temperature =  $-253^{\circ}$ C

#### Figure 29:

Fuel Force on LH2 Tank

Outline	4		ANICHE
Filter: Name •		tatic Structural	ANSYS
🔄 🖉 t> ⊞ 🗟 斜		e 60.3	2019 <b>R1</b>
Project     Prodel (An)     P		19.2023 00.27 PM  Fore 2: 1.3424+006 N  Component: 0, 1.3024+006,0 N	ACADEMIC
Details of "Force 2"	7	0.00 450.00 900.00 (mm)	Z <b>Z</b> X
- Scope		225.00 675.00	
Scoping Method Geometry Selection			
Geometry 2683 Faces	Geor	netry / Print Preview / Report Preview /	
Definition	Graph	9 Tabular Data	9
Type Force		50 Steers Time foll w X (M) w X (M)	
Define By Components			
Coordinate System Global Coordinate	ystem	2 1 60 0 10/24e.006 0	
X Component 0. N (ramped)	-1.0	M24e+6	
Y Component -1.0424e+006 N (ra	nped)	60.	
Z Component 0. N (ramped)			
Suppressed No			

### Figure 30:

LH2 Fuel Temperature

Outline	ą	
Filter: Name	•	ANSYS
3 27 t> E 61	61	Time: 60.3 2019 R1
Project		12-08-2023 08:27 PM A C A D E M I C
Hodel (A4)     Hodel (A4)     Hodel (A4)     Material     Material     Josephilie Connector     Material     Josephilie Connector     Statics Connector     Statics Connector     Material     Josephilie Connector     Josephilie Connector	y te Systems ore <b>Tructural (AS)</b> Jaya Settoga Andref Sark Torushy ed Saport or 2 or 2 3 Salvan Information 3 Salvan Information 9 Salvan Information 9 Eau/aeth Stress 6 Sank	Thermal Condition: -23.*C
Details of "Thermal Con	dition" a	0.00 450.00 900.00 (mm) Z
- Scope		225.00 675.00
Scoping Method Ge	ometry Selection	
Geometry 500	Bodies	Geometry / Print Preview / Report Preview /
<ul> <li>Definition</li> </ul>		Graph a Tabular Data
Type The	ermal Condition	FO Stees Time (d) V Temperature (*C)
Magnitude -25	i3. °C (ramped)	
Suppressed No		2 1 6053.
		233

## Figure 31:

Earth Gravity on LH2 Tank

Outline			
Filter: Name	•	A Static Structural Structural	ANSYS
3 A D H	S 1	Time: 60.3	2019 <b>R1</b>
Project     Project		12-08-2022 DB25 PM	CADEMIC Y
Details of "Standard	d Earth Gravity"	a 0.00 450.00 900.00 (mm) 2-	- x
Scope		225.00 675.00	
Geometry	All Bodies		
<ul> <li>Definition</li> </ul>		\Geometry / Print Preview / Report Preview /	
Coordinate Syste	em Global Coordinate System	Granh 9 Tabular Data	9
X Component	0. mm/s <sup>2</sup> (ramped)	sa Stars Time fel [rf V frem (c)] [rf Z frem (c)]	
Y Component	-9806.6 mm/s <sup>2</sup> (ramped)		
Z Component	0. mm/s <sup>2</sup> (ramped)		
Suppressed	No	-9806.6	
Direction	-Y Direction	60.	

## Figure 32:

Fixed Support for LH2 Tank

Outline	
Filter: Name 💌	A:Static Structural ANSYS
🕼 🕢 🕬 🖽 😖 🛔	Time: 60. 3 2019 R1
Image: Construction       Project         Image: Construction       Image: Construction         Image: Construction       Image: Construction	
Details of "Fixed Support"	0.00 450.00 900.00 (mm) 2 - X
Scope	225.00 675.00
Scoping Method Geometry Selection	
Geometry 4 Edges	Ceometry APnnt Preview A Report Preview /
- Definition	Graph P Tabular Data P
Type Fixed Support Suppressed No	
	60.

# 3.5.4 External Fuel Tank of Launch Vehicle **Figure 33:**

EFT Mesh Settings

Outline 7		a hugh real
Filter: Name 👻		ANSYS
@ 21 t> ⊞ <b>@</b> \$ <b>!</b>		2019 <b>R1</b>
Project*	A	
Details of "Mesh"		
- Display		
Display Style Use Geometry Setting		
- Defaults		
Physics Preference Mechanical		
Element Order Program Controlled		
Element Size Delatit		
- Stony		
Perclution Default (2)		
Marb Defasturing Ver		
Defeature Size Default		
Transition Fast		
Span Apple Center Coarse		
Initial Size Seed Assembly		
Bounding Box Di., 4895.0 mm		
Average Surface 11178 mm <sup>2</sup>		
Minimum Edge L., 0.61188 mm		
Quality		
Check Mesh Qua Yes, Errors		Y
Error Limits Standard Mechanical		
Target Quality Default (0.050000)		T
Smoothing Low		1
Mesh Metric None		A.
Inflation	0 2e403 4e403 (mm) 7	<b>N</b> .
Advanced	2010 4000 ((iiii)) 2	
Statistics	1e+03 3e+03	
	2 CONTRACTOR AND A	
	Geometry / Print Preview / Report Preview /	

• Boundary Conditions for FEA Analysis

#### Wind Force Calculation

It is assumed that the launch will happen in Cornwall City, and wind will flow in the -Z Direction as the geometry is symmetric.

(BeachWeather, n.d.)

Highest Temperature in Cornwall =  $34^{\circ}C$ 

Wind Speed in Cornwall = 22 MPH = 9.835 m/s

Density of air at sea level =  $1.229 \text{ kg/m}^3$ 

Area of the plate hitting by  $air = 3872.0835 \text{ m}^2$ 

Mass of the air = Density x Area = 1.229 x 3872.0835

Mass of the air = 4758.7906 kg/m

Acceleration =  $(Windspeed)^2 = (9.835)^2 = 96.727 \text{ m/s}^2$ 

Force = Mass x Acceleration

Wind Force = 4758.7906 x 96.727

Wind Force = 331816.1937 N

Due to the RAM limitations and the massive size of the model, it has been scaled down by 1:10.

Wind Force = 331816.1937 / 10

Wind Force = 33181.61937 N

## Figure 34:

Wind Force on EFT

Outline		4	
Filter: Name 👻		A: Static Structural	ANSYS
] 🗟 		Force 0. 3	2019 <b>R1</b>
Project*     Model (A4     Model)     Model (A4     Model)     Model (A4     Model)     Model     Mod	b) cbr	1.402-003 11394M Composents 0.0,-3229+005 N Composents 0.0,-3229+005 N	CADEMIC
Details of Porce		0 3e+03 6e+03 (mm) Z	- x
Scoping Method	Geometry Selection	1.5e+03 4.5e+03	
Geometry	10 Faces		
Definition		V country value review V vebout review V	
Туре	Force	Graph 7 Tabular Data	4
Define By	Components	60. Steps Time [s] 🔽 X [N] 🔽 X [N]	
Coordinate System	Global Coordinate System	0	
X Component	0. N (ramped)	2 1 60. 0. 03.229e+005	
Y Component	0. N (ramped)	-3.4296+5	
Z Component	-3.229e+005 N (ramped)	0.	
Suppressed	No		

## Figure 35:

LOX Fuel Temperature



## Figure 36:

LH2 Fuel Temperature

Outline		3	
Filter: Name •		A Static Structural Thermal Condition 2	ANSYS
3 A D H	S 1	Time: 60.3	2019 <b>R1</b>
Project*     Project*	a)     1       wd)     netty       netty     netty       nettors     Status       nettors     Status       b     Nettors       b     Standard Earth Gravity       read Sectors     Standard Earth Gravity       read Sectors     Standard Earth Gravity       read Sectors     Themal Goadian 2       Themal Goadian 2     Status (Ad)       Status (Ad)     Status (Ad)       Status (Ad)     Status (Ad)       Status (Ad)     Status (Ad)	The doub of the second	АСА <b>ДЕМІС</b> ¥ <b>†</b>
Details of "Thermal	Condition 2"	8	
- Scope		0 3e+03 6e+03 (mm)	-
Scoping Method	Named Selection	1.5e+03 4.5e+03	
Named Selection	LH2Tank	Geometry (Diet Brains) Parent Denies /	
E Definition		Cecountry Shink Sherrow Vielous Sherrow	
Туре	Thermal Condition	Graph P Tabular Data	ą.
Magnitude	-253. *C (ramped)	60. Steps Time [s] 🗹 Temperature [*C]	
Suppressed	No	34. • • • • • • • • • • • • • • • • • • •	

## Figure 37:

Earth Gravity on EFT

Outline		
Filter: Name •		ANSYS
🗟 🕢 🎶 🖽		2019 R1 2019
Project     P	4) metry metry intrials inclose indicate Systems inclose indicate Systems inclose indicate Systems indicate Sy	12-09-2023 11:35 PM     A C A D E M I C       Brandard Earth Grouply: 9806 6 mm/s <sup>3</sup> Components: 0, 9806 6 3: nm/s <sup>4</sup> Components: 0, 9806 6 3: nm/s <sup>4</sup> Image: Components: 0, 9806 6 3: nm/s <sup>4</sup>
Details of "Standard	Earth Gravity"	a 1.5e+03 4.5e+03
Scope		Geometry / Print Preview /
Geometry	All Bodies	Caret I Think Day
Definition		Viapn * Iabular vata
Coordinate Syste	m Global Coordinate System	60. Steps Time [s] [ X [mm/s'] [ X [mm/s'] ] Z [mm/s']
X Component	0. mm/s <sup>2</sup> (ramped)	0.0 = 0. = 0. = 0.
Y Component	-9806.6 mm/s <sup>2</sup> (ramped)	2 1 50. 09906.6 0.
Z Component	0. mm/s <sup>2</sup> (ramped)	60.
Suppressed	No	
Direction	-Y Direction	

## Figure 38:

Fixed Support for EFT

Outline 9				ANGVO
Filter: Name 👻	A: Static Structural Fixed Support			ANSYS
[ ]  → ±	Time: 60. s			2019 <b>R1</b>
Project*	12-08-2023 11:56 PM			
🗐 🙀 Model (A4)	Evend Support			
E Geometry	Tixed support			
Construction Geometry				
Coordinate Systems				
E-Connections				
E				
Static Structural (A5)				
Analysis Settings		ALC: N. C.		
Standard Earth Gravity				
- Se Force				
Thermal Condition				
Thermal Condition 2			e	Y.
Solution (A6)				+
Total Deformation				
		0 3e+0	3 6e+03 (mm)	z <b>z x</b>
		15:00	45++//9	
Details of "Fixed Support" 4		1.56403	456765	
Scope	Geometry (Print Preview) Report Preview/			
Geometry 8 Edges	Graph		4 Tabular Data	q
Definition			60.	
Type Fixed Support				
Suppressed No				
			60.	

## 4.0 Results

### 4.1 500x500x25 mm Plate

Deformation outcomes in ANSYS Workbench may often be represented as either total deformation or directed deformation. Both of these methods are used to derive displacements based on the analysis of stresses. In this particular instance, the overall distortion has been duly considered. The observed maximum deformation was 0.00051977 mm, indicating a very modest magnitude.

#### Figure 39:





According to the data shown in Figure 40, the highest equivalent stress observed on the plate is determined to be 0.07055 Mpa. The yield strength of aluminium alloy 2195 is measured to be 230 megapascals (MPa). The most incredible equivalent stress experienced by the plate is determined to be 0.07 MPa, a value far lower than the yield strength.

#### Figure 40:



500x500x25 mm Plate's Equivalent Stress

Figure 41 depicts the Equivalent elastic strain acting on the plate. The maximum strain that has been acting on the plate is  $9.95 e^{-7}$ .

#### Figure 41:





#### 4.2 Liquid Oxygen Tank

Figure 42 and Figure 43 represent the total deformation of the LOX Tank as well as a sectional view of the LOX Tank's total deformation, respectively. It was determined that the tank had a maximum distortion of 12.354 millimetres. The model is scaled down by 1:10, so the maximum deformation is 123.54 mm. In addition, the precise position of the highest deformation that has been created is shown in Figure 43. Even if the degree of deformation is rather significant, there is still a possibility of reaching fatigue with repeated use; this is something that will need to be investigated in the future.

#### Figure 42:





#### Figure 43:

Sectional View of LOX Tank's Total Deformation



Figure 44 and 45 show the equivalent stress on the LOX Tank. The maximum stress was found to be 14898.0 MPa. Although most of the tanks had equivalent stress between 1.9758 MPa and 1657.1 Mpa, there have been very few points on the LOX tank's surface where the stresses reached up to 14898.0 MPa. This will lead to the breaking of the tank as it exceeds the yield stress point.

### Figure 44:





#### Figure 45:

Sectional View of LOX Tank's Equivalent Stress



Figure 46 and 47 show the Equivalent elastic strain of the fuel tank. The maximum strain on the fuel tank is found to be 0.21081.

#### Figure 46:

LOX Tank's Equivalent Elastic Strain



#### Figure 47:





#### 4.3 Intertank

Figure 48 illustrates the total deformation of the Intertank, while Figure 49 presents a sectional view of the total deformation of the Intertank. The investigation revealed that the tank had a maximum deformation of 0.022 mm. The model is scaled down by 1:10. The maximum deformation is 0.22508 mm. Figure 49 depicts the precise spot wherever the most significant degree of deformation has been generated as an outcome of the loads acting. Despite the negligible magnitude of distortion, which may not need explicit acknowledgement, there is no possibility that prolonged use might result in fatigue.

#### Figure 48:

Intertank's Total Deformation

A: Static Structural Total Deformation Unit: mm Time: 60 25-07-202 11:14 PM		ANSYS 2019 R1 ACADEMIC
0.022508 Max 0.02007 0.01506 0.015005 0.015005 0.010004 0.0050018 0.0050018 0.0050018 0.005009 0 Min		Ť
	0.00 500.00 1000.00 (mm) 250.00 750.00	z

#### Figure 49:

Sectional View of Intertank's Total Deformation



Figures 50 and 51 depict the similar stress experienced by the Intertank. The investigation determined that the most significant stress observed was 31.246 MPa. The majority of the tank's surface exhibited very low levels of stress. There is no potential for fatigue in this particular circumstance, unlike the scenario described in section 4.2.

#### Figure 50:





#### Figure 51:

Sectional View of Intertank's Equivalent Stress



Figure 52 and 53 shows the Equivalent elastic strain of the fuel tank. The maximum strain on the fuel tank is found to be  $4.65 e^{-4}$ .

#### Figure 52:





#### Figure 53:

Sectional View of Intertank's Equivalent Elastic Strain



#### 4.4 Liquid Hydrogen Tank

Figure 54 depicts the total deformation of the Liquid Hydrogen Tank, while Figure 55 provides a cross-sectional perspective of the overall deformation of the Liquid Hydrogen Tank. The findings of the examination indicated that the tank exhibited a maximum deformation of 3.6 mm. This model is scaled down by 1:30. Maximum deformation is 108

mm. Figure 55 illustrates the specific location where the most amount of deformation has been created as a result of the applied loads.

#### Figure 54:

LH2's Total Deformation



#### Figure 55:

Sectional View of LH2's Total Deformation



Figures 56 and 57 depict the equivalent stress experienced by the LH2 Tank. The experimental analysis yielded a maximum stress value of 2706.9 MPa. So, the model is scaled down by 1:30. Maximum stress is 81270 MPa.

#### Figure 56:





#### Figure 57:

Sectional View of LH2's Equivalent Stress



Figure 58 and 59 show the Equivalent elastic strain of the fuel tank. The maximum strain on the fuel tank is found to be 1.1437.

#### Figure 58:





#### Figure 59:

Sectional View of LH2's Equivalent Elastic Strain



#### 4.5 External Fuel Tank of Launch Vehicle

Figure 60 illustrates the total deformation of the External Fuel Tank, while Figure 55 presents a cross-sectional view of the total deformation of the External Fuel Tank. According to the results of the investigation, it was seen that the tank had a maximum distortion of 6.7 mm. But the model is scaled down by 1:10. So the maximum deformation is 67.602 mm. Figure 49 depicts the precise place where the highest level of deformation has been generated due to the

exerted loads. The potential for significant deformation is noteworthy, given the inherent risk of tank collapse.

#### Figure 60:





#### Figure 61:

Sectional View of EFT's Total Deformation



Figures 62 and 63 illustrate the equivalent stress encountered by the EF Tank. The experimental study resulted in a maximum stress value of 427130 MPa. The stress levels observed in the tank were mainly within the range of 0.128 MPa to 2000 MPa. However, a few particular spots on the surface of the EF tank revealed much higher stress values, reaching up to 427130 MPa. The tank's structural integrity will be compromised due to exceeding its yield stress limit.

#### Figure 62:

EFT's Equivalent Stress



#### Figure 63:

Sectional View of EFT's Equivalent Stress



Figure 64 and 65 show the Equivalent elastic strain of the fuel tank. The maximum strain on the fuel tank is found to be 6.6593.

#### Figure 64:





### Figure 65:

ACCOUNT OF A CONSTANT OF A CON

Sectional View of EFT's Equivalent Elastic Strain

## 5.0 Mesh Sensitivity

A mesh sensitivity analysis involves conducting many simulations with grids of varying resolutions and afterwards evaluating the extent to which the converged solution is altered with each mesh. In conducting a mesh sensitivity analysis, ensuring a substantial disparity in grid resolution between consecutive meshes is essential. This is crucial since there needs to be a more significant change in findings due to little refining might lead to a misleading perception of mesh independence (Wodo et al.,2011). In order to address this concern, a comprehensive examination of mesh sensitivity was conducted on all components, using a mesh element size variation of 2 mm for each simulation.

#### 5.1 Intertank

#### Figure 66:

Intertank Mesh Sensitivity Table

Table of Design Points 🗸 🗸 🗸					⊸ д Х		
	A	В	с	D	E	F	G
1	Name 💌	P1 - Mesh Element Size 💌	P2 - Total Deformation Maximum 💌	P3 - Equivalent Stress Maximum 💌	📃 Ret	Retained Data	Note 💌
2	Units	mm 💌	mm	MPa			
3	DP 0 (Current)	50	0.0033325	5.6341	V	×	
4	DP 1	25	0.0032636	7.7009			
5	DP 2	13	0.0033024	7.187			
6	DP 3	7	0.0033223	16.253			
7	DP 4	5	0.0033372	17.506			
8	DP 5	4	0.0033297	12.986			
*							

#### Figure 67:





## 5.2 Liquid Hydrogen Tank

## Figure 68:

LH2 Mesh Sensitivity Table

Table of Design Points 🗸 🗸 🕇							
	А	В	С	D	E	F	G
1	Name 💌	P1 - Mesh Element Size 💌	P2 - Total Deformation Maximum 💽	P3 - Equivalent Stress Maximum 💌	📃 Ret	Retained Data	Note 💌
2	Units	mm 💌	mm	MPa			
3	DP 0 (Current)	50	3.6953	2706.9	V	×	
4	DP 1	25	3.6477	2274.7			
5	DP 2	15	3.6983	8406.6			
6	DP 3	14	3.7002	16544			
7	DP 4	13	3.7004	18118			
8	DP 5	12	3.7035	20456			
9	DP 6	11	3.7064	33127			
10	DP 7	10	3.706	26710			
11	DP 8	9	3.7044	23409			
*							

## Figure 69:

LH2 Mesh Sensitivity Graph



## 6.0 Conclusion

To summarise, this report presents and discusses the findings of the deformation study conducted on many components of the launch vehicle, including the 500x500x25 mm plate, Liquid Oxygen (LOX) tank, Intertank, Liquid Hydrogen (LH2) tank, and External Fuel Tank (EFT). The study encompassed the assessment of total deformation, equivalent stress, and equivalent elastic strain for every component.

The 500x500x25 mm plate exhibited a maximum measured deformation of 0.00051977 mm, suggesting a rather little level of distortion. The magnitude of the stress sustained by the plate was far below the yield strength of the material. Concerns were raised over probable fatigue due to prolonged usage of the LOX tank, since it exhibited a maximum deformation of 12.354 millimetres, a significant value warranting attention. The stress levels hit a crucial threshold, beyond the yield stress of the material, hence posing a risk of tank failure.

In the case of the Intertank, it was seen that the greatest deformation experienced was measured to be 0.022 mm. Additionally, the corresponding stress levels were found to be quite low, indicating a less likelihood of encountering fatigue-induced problems. The LH2 tank demonstrated a notable maximum distortion of 3.6 mm, which, when extrapolated, amounted to 108 mm. The attained stress level of 2706.9 MPa is considerable, potentially jeopardising the structural integrity of the tank.

A maximum deformation of 67.602 mm was found in the instance of the External Fuel Tank (EFT). The stress equivalent exhibited localised regions characterised by very elevated stress levels, potentially jeopardising the integrity of the tank.

In general, several elements had minor distortions and stress levels that were below acceptable thresholds, while others gave rise to apprehensions regarding possible fatigue and structural soundness concerns. The aforementioned findings underscore the significance of continuous inquiry and assessment in order to guarantee the safety and dependability of these components throughout operating circumstances.

## 7.0 Future Work

## 7.1 Dynamic Analysis

The primary objective of dynamic analysis is to gain insight into the response of structures when subjected to dynamic loads, including but not limited to vibrations, shock, and impact. Ensuring the ability of the proposed composite plate design to endure the intricate and sometimes uncertain circumstances encountered during launch and flight is of utmost importance.

Steps:

- Scenario Simulation for Dynamic Loading: This simulation aims to replicate a range of dynamic loading situations, encompassing vibrations experienced during launch, abrupt accelerations, and probable collisions.
- Modal analysis is conducted in order to ascertain the natural frequencies, mode shapes, and possible resonance concerns of the composite plate when subjected to dynamic loads.
- The objective of this study is to analyse the frequency response of a composite plate subjected to various frequency inputs, with the aim of reproducing the dynamic conditions experienced during launch and flight.
- The transient dynamic analysis is employed to simulate and analyse time-dependent phenomena, such as abrupt accelerations or impact events, to assess the plate structure's response over a certain period.

### 7.2 Experimental Validation

The validation of experiments is of utmost importance in order to verify the precision of the Finite Element Analysis (FEA) model and evaluate the practical performance of the composite plate design being suggested, when subjected to real-world conditions. This stage entails conducting physical experiments to compare the anticipated behaviour with observed outcomes.

Steps:

- Prototype Manufacturing: The objective is to produce a reduced-scale prototype of the composite plate utilising the chosen aluminium alloy and graphene-based composite materials.
- The proposed methodology involves the installation of strain gauges, accelerometers, and many other sensors onto the prototype in order to quantify its reaction to diverse dynamic loads.
- Vibration Testing: Conduct controlled vibration testing on the prototype to replicate launch circumstances. Gather empirical evidence pertaining to the phenomena of deflection, stress distribution, and resonance behaviour.
- Shock and impact testing involves the simulation of impact scenarios through the controlled application of impact loads on the prototype. Assess the responsiveness and structural robustness of the subject.
- Comparison with Finite Element Analysis (FEA): The experimental data is compared with the FEA predictions in order to assess and validate the correctness of the model. The Finite Element Analysis (FEA) parameters should be adjusted if deemed required.

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### 9.0 Presentation Reflection

Faculty of Engineering, Environment & Computing (EEC)

## MSC THESIS PROJECT PRESENTATION

FEA modelling of the Aluminium alloy with a graphene-based composite plate for the structural application in the launch vehicle's external fuel tank. Supervisor – Dr. Ashwath Pazhani Department of Automotive Engineering

## CONTENT

Introduction Project Aim Project Objectives Gantt Chart Background & Need of the Project Model Analysis References



## **PROJECT AIM**

Investigation of the feasibility of using aluminium alloy with a graphene -based composite plate for structural application in the fuel tanks of launch vehicles through FEA modelling.

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## **PROJECT OBJECTIVES**

- Literature review of FEA modelling of the aluminium alloy with a graphene -based composite plate for the launch vehicle external fuel tank structural application.
- Developing a model and validating it against experimental data.
- Analyzing composite plates under various conditions such as thermal, mechanical loads, stress and strain, etc.
- Comparing results with the current material used for the external tank of the launch vehicle.
- Conducting cost analysis of manufacturing and comparing it with other materials.
- Identifying any challenges or limitations.

## **GANTT CHART**

5

6



Courtesy - Gantt Project

#### **BACKGROUND & NEED OF THE PROJECT**

• 2195 Aluminium Alloy with 0.5% wt. Graphene Density = 2670 kg/m<sup>3</sup>. Tensile Yield Strength = 230 MPa. Compressive Yield Strength = 270 MPa. Tensile Ultimate Strength = 510 MPa. Compressive Ultimate Strength = 490 MPa.

• Needs Lightweight Design. Increased Strength & Stiffness. Improved Fuel Efficiency.







Courtesy - Ansys

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## CALCULATION

#### • For LOX Tank

Wind Speed in Cornwall = 22 miles/ hr. = 9.835 m/s. Area of tank hitting by air =  $747974128.53 \text{ mm}^2 = 747.9741 \text{ m}^2$ . Mass of the body =  $1.229 \text{ kg/m}^3 x 747.97 \text{ m}^2 = 919.26 \text{ kg/m}$ . Acceleration = (Windspeed)<sup>2</sup> = (9.835)<sup>2</sup> =  $96.727 \text{ m/s}^2$ . Force = Mass x Acceleration = 919.26 x 96.727Force = 88916.79 N.

• For Intertank Force = 21646.044 N

• For LH2 Tank Force = 190666.41 N

• For 500x500x25 mm Plate Force = 1.4799 N

(Lockheed Martin Space Systems Company, 2008) (Beach Weather, n.d.)

## CALCULATION

#### • For LOX Tank

Density of Liquid Oxygen= 1.141 kg/L = 1.141 g/mL. Amount of Liquid Oxygen in Tank= 145000 Gallons. Kilograms = Gallons x 3.7854 x Density Kilograms = 145000 x 3.7854 x 1.141 Fuel Force = 626277.45 N. Fuel temperature = - 147.222°C

• For LH2 Tank Density of Liquid Hydrogen = 0.07085 kg/L = 0.07085 g/mL. Amount of Liquid Hydrogen in Tank= 390000 Gallons. Fuel Force = 1042420.41 N Fuel Temperature = - 253°C

(NASA, 2011)





## **MESH SENSITIVITY**



Name	P1 - Mesh Element Size	P2 - Total Deformation Maximun
Units	mm	mm
DP0 (Current)	50	3.695295081
DP1	25	3.64770933
DP 2	15	3.69830104
DP 3	14	3.700241864
DP4	13	3.700406368
DP5	12	3.703495199
DP6	11	3.706430401
DP7	10	3.70595376
DP8	9	3 704385897

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Courtesy – Excel

## **DRAWBACKS**

- Material Cost
- Manufacturing Complexity
- Availability of Limited Data

## **FUTURE WORK**

- Dynamic Analysis
- Experimental Validation

# REFERENCES

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Following receiving a lot of feedback about my previous presentation, I am pleased to give my views and insights.

I am very delighted with the favourable response of the presentation. I find it rewarding to learn that the supervisor and assessor expressed their appreciation for my diligent work in organising and efficiently delivering the information. This criticism serves as an encouragement for me to further refine my presenting abilities and uphold the rigorous standards that I have established for myself.

I acknowledge the significance of integrating comprehensive elucidations and visual aids inside my presentation, particularly when addressing intricate elements such as ANSYS. In order to optimise report, my intention was to prioritise the incorporation of more extensive elucidations substantiated by pertinent visual aids such as photos and diagrams derived from ANSYS. By implementing this approach, not only will the comprehension of the audience be enhanced, but the information will also become more captivating and easily comprehensible.
"Have you scaled down the model?" This inquiry compels me to reexamine a fundamental element of my presentation. Although I provided an overview of the model, it seems that further explanation regarding whether the model was scaled down or not is required. In presentations that involve intricate models, I will take care to explicitly acknowledge this feature in order to mitigate any potential uncertainty and facilitate a more full comprehension of the project.

In summary, I express my gratitude for the invaluable feedback that has been provided to me. The feedback I received has offered valuable guidance on enhancing the depth of my information, using effective visual aids, and addressing possible sources of misunderstanding. I am steadfast in using these teachings in my forthcoming speeches to augment their general calibre and efficacy. I express my gratitude for your excellent input, as I perceive it as a significant chance for personal development and improvement.

## • Appendices

## > Ethics Approval

FEA modelling of the aluminum alloy graphene based composite plate for the launch vehicle external fuel tank structural application

**Coventry** University

P151945

## **Certificate of Ethical Approval**

Applicant:

Project Title:

Neeraj Salunkhe

FEA modelling of the aluminum alloy graphene based composite plate for the launch vehicle external fuel tank structural application

This is to certify that the above named applicant has completed the Coventry University Ethical Approval process and their project has been confirmed and approved as Low Risk

Date of approval:	12 May 2023					
Project Reference Number:	P151945					

Neeraj Salunkhe (7166MAA)

Page 1

12 May 2023

## ➢ Gantt Chart

GANTT Project	$\Rightarrow$	20	123							1	1		1	1		
Name	Begin En	d d	Week 19 7/5/23	Week 20 14/5/23	Week 21 21/5/23	Week 22 28/5/23	Week 23 4/6/23	Week 24 11/6/23	Week 25 18/6/23	Week 26 25/6/23	Week <b>27</b> 2/7/23	Week 28 9/7/23	Week 29 16/7/23	Week 30 23/7/23	Week 31 30/7/23	Week (
Gaining Background Information	5/5/23 12/5	5/23														
Finalising Aim & Objectives	13/5/23 19/5	5/23	ĺ													
Literature Review	20/5/23 26/5	5/23		ĺ												
Gathering Loading & Thermal Conditions	27/5/23 2/6/	/23			Ĺ											
Development of External Tank	3/6/23 9/6/	/23				Ĺ	_	1								
Analysing Model	10/6/23 16/6	6/23					(									
Comparison of Analysis with Current Material	17/6/23 28/6	6/23						ĺ								
<ul> <li>Cost Analysis</li> </ul>	29/6/23 8/7/	/23										Ŀ,				
Viva Presentation Preparation	10/7/23 17/7	7/23														
<ul> <li>Making Report</li> </ul>	10/7/23 26/7	7/23														
<ul> <li>Finalising Report</li> </ul>	27/7/23 7/8/	/23												Ľ		